

# NVMeSW IP Core reference design manual

Rev1.0 24-Apr-19

## 1 NVMe

NVM Express (NVMe) defines the interface for the host controller to access solid state drive (SSD) by PCI Express. NVM Express optimizes the process to issue command and completion by using only two registers (Command issue and Command completion). Also, NVMe supports parallel operation by supporting up to 64K commands within single queue. 64K command entries improve transfer performance for both sequential and random access.

In PCIe SSD market, two standards are used, i.e. AHCI and NVMe. AHCI is the old standard to provide the interface for SATA hard disk drive while NVMe is optimized for non-volatile memory, like SSD. The comparison between both AHCI and NVMe protocol in more details is described in “A Comparison of NVMe and AHCI” document.

[https://sata-io.org/system/files/member-downloads/NVMe%20and%20AHCI %20 long .pdf](https://sata-io.org/system/files/member-downloads/NVMe%20and%20AHCI%20long.pdf)

The example of NVMe storage device is shown in <http://www.nvmexpress.org/products/>.

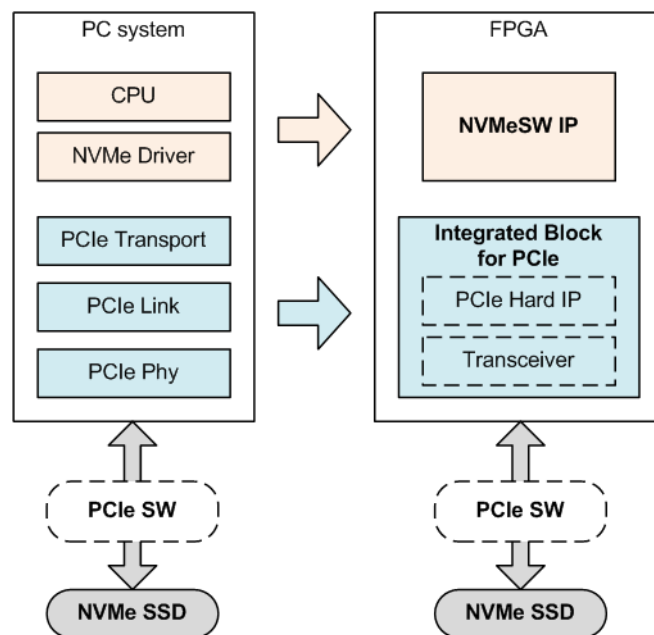


Figure 1-1 NVMe protocol layer

To access NVMe SSD, the general system implements NVMe driver running on the processor, as shown in the left side of Figure 1-1. The physical connection of NVMe standard is PCIe connector which is one-to-one type, so one PCIe host can connect to one PCIe device. When many SSDs must be connected to the one host, PCIe switch must be applied to extend the number of SSDs. When PCIe switch is applied, the driver on the processor must support to scan the NVMe SSD operating under PCIe switch.

NVMeSW IP implements NVMe driver to access NVMe SSD and the function to scan NVMe SSD through one PCIe switch by using pure-hardware logic. So, user can access NVMe SSD without including any processor and driver by using NVMeSW IP in FPGA board.

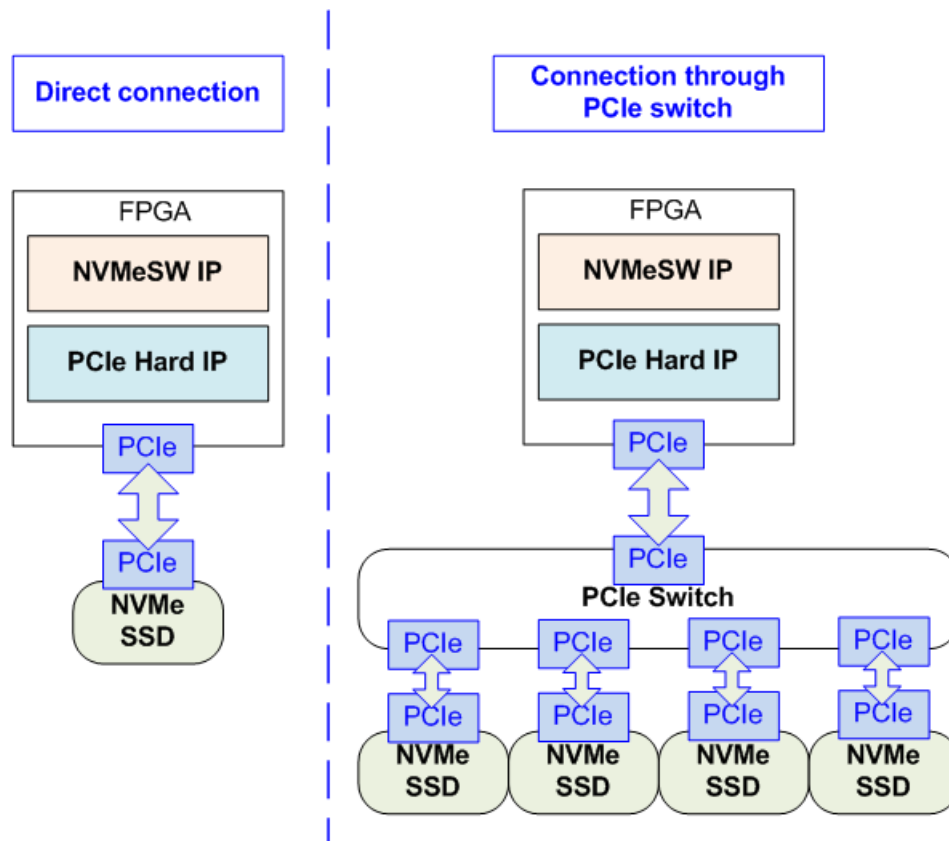


Figure 1-2 Direct connection and PCIe switch connection

Figure 1-2 shows two hardware connections for connecting NVMeSW IP to NVMe SSD. The left side is the direct connection when one PCIe SSD is applied. PCIe connector of FPGA connects to an NVMe SSD without the intermediate hardware.

The right side shows the connection through PCIe switch when multiple SSDs must be controlled by one NVMeSW IP. Though the number of connected SSDs is increased, transfer speed is same. NVMeSW IP can operate with one SSD at a time. Also, the latency to transfer packet between NVMeSW IP and the NVMe SSD is increased when connecting the SSD through PCIe switch. Write performance of some SSDs may be little dropped because of more latency time.

According to PCIe specification, one PCIe switch supports up to 32 NVMe SSDs, but NVMeSW IP is designed to support up to 4 NVMe SSDs. Supporting more devices is as optional.

## 2 Hardware overview

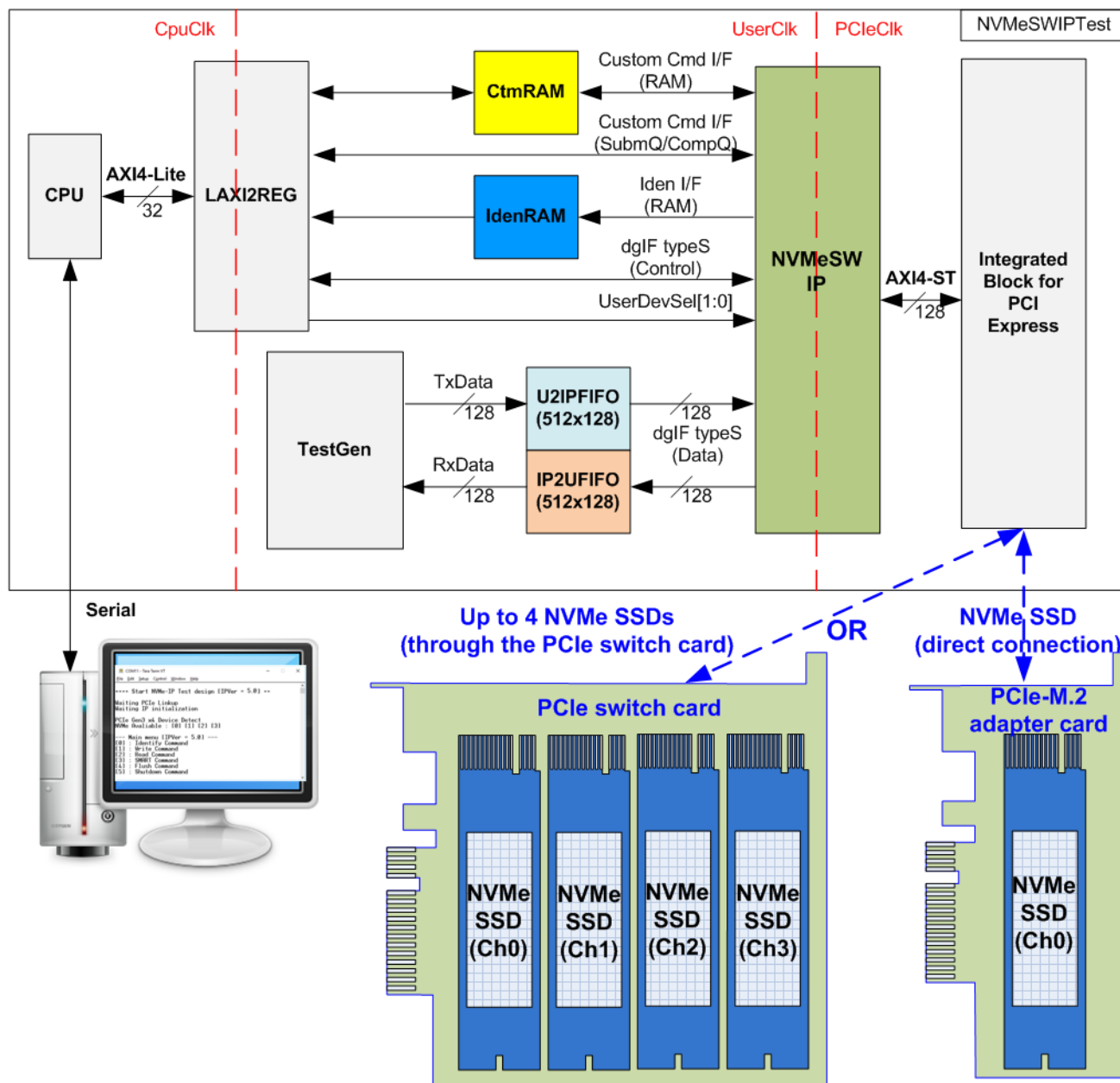


Figure 2-1 NVMeSW IP demo hardware

The hardware system can be split into three groups, i.e. TestGen, NVMe, and CPU. TestGen is the test logic to generate test data stream for NVMeSW IP through U2IPFIFO. Also, TestGen reads data stream output from NVMeSW IP through IP2UFIFO, and then verify it. NVMe includes the NVMeSW IP and the PCIe hard IP (Integrated Block for PCI Express). NVMe supports to access NVMe SSD directly or through PCIe switch. CPU and LAXI2Reg are designed to interface with user through Serial interface. User can set command and the test parameters through Serial console. Also, the current status of the test hardware is monitored by user through Serial console. The CPU firmware must be implemented to control the sequence for operating each command.

There are three clock domains displayed in Figure 2-1, i.e. CpuClk, UserClk, and PCIeClk. CpuClk is the clock domain of CPU and its peripherals. This clock must be stable clock which is independent from the other hardware interface. PCIeClk is the clock output from PCIe hard IP to synchronous with data stream of 128 bit AXI4 stream bus. When the PCIe hard IP is set to 4 lane PCIe Gen3, PCIeClk frequency is equal to 250 MHz. UserClk is the example user clock domain which is independent from the other clock domains. So, UserClk is the main clock domain for running the user interface of NVMeSW IP, RAM, FIFO, and TestGen. According to NVMeSW IP datasheet, clock frequency of UserClk must be more than or equal to PCIeClk. In this reference design, UserClk is equal to 275 MHz.

To test data interface of NVMeSW IP, four memory blocks are implemented, i.e. CtmRAM, IdenRAM, U2IPFIFO, and IP2UFIFO. CtmRAM stores returned data from SMART command while IdenRAM stores returned data from Identify command. U2IPFIFO stores data for Write command while IP2UFIFO stores data for Read command. TestGen is designed to monitor flow control signal of U2IPFIFO and IP2UFIFO to be always read and write data when the FIFO is ready. So, the FIFO depth is not large by setting to 512 x 128 bit and implemented by BlockRAM. When running SMART command or Identify command, the returned data from the command is processed on CPU. So, another side of CtmRAM and IdenRAM is connected to LAXI2Reg to allow CPU accessing through AXI4-Lite bus.

More details of the hardware are described as follows.

## 2.1 TestGen

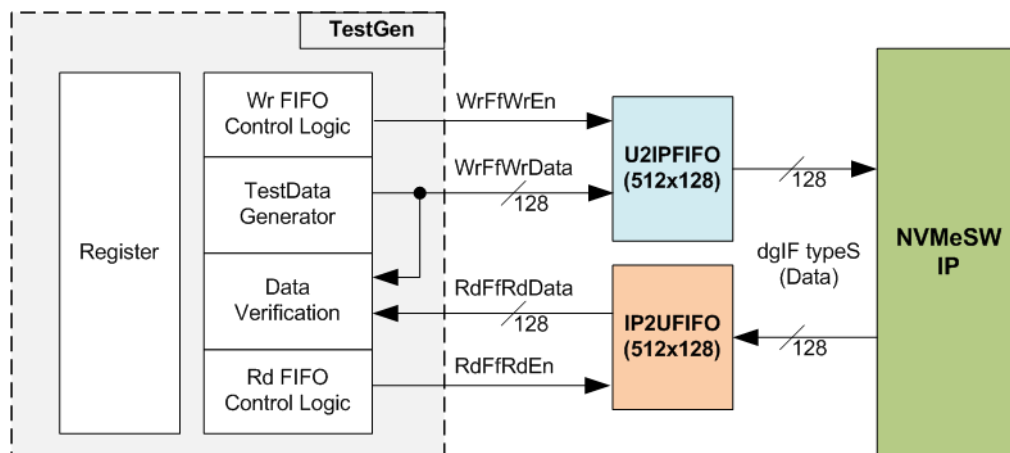


Figure 2-2 TestGen interface

TestGen module is the test logic to send test data to NVMeSW IP through U2IPFIFO when operating Write command. Also, the test data is fed to be the expected value to verify the read data from NVMeSW IP through IP2UFIFO when operating Read command. Control logic asserts Write enable and Read enable to '1' when the FIFOs are ready. Data bandwidth of TestGen is matched to NVMeSW IP by running at the same clock and using same data bus size, so NVMeSW IP can transfer data with U2IPFIFO and IP2UFIFO without waiting data ready. As a result, the test logic shows the best performance to write and read data with the SSD through NVMeSW IP.

Register file in the TestGen receives test parameters from user, i.e. total transfer size, transfer direction, verification enable, and test pattern selector. So, the internal logic includes the counter to control total transfer size of test data. The details of hardware logic of TestGen are shown in Figure 2-3.

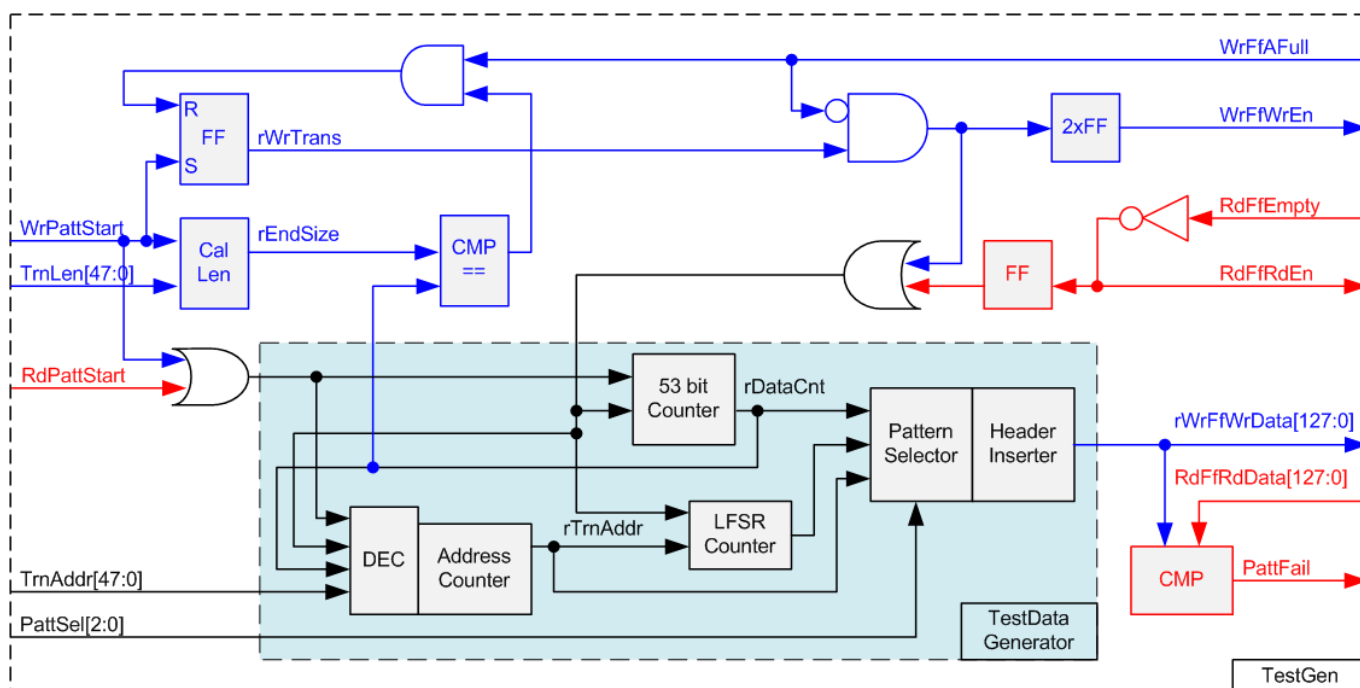


Figure 2-3 TestGen hardware

As shown in the right side of Figure 2-3, flow control signals of FIFO are WrFfAFull and RdFfEmpty. When FIFO is almost full during write operation (WrFfAFull='1'), WrFfWrEn is de-asserted to '0' to pause data sending to FIFO. For read operation, when FIFO has data (RdFfEmpty='0'), the logic reads data from FIFO to compare with the expected data by asserting RdFfRdEn to '1'.

The logic in the left side of Figure 2-3 is designed to count transfer size. When total data count is equal to the end size (set by user), write enable or read enable of FIFO is de-asserted to '0'. So, the total data count to write FIFO or read FIFO is controlled by user.

The lower side of Figure 2-3 shows the details to generate test data for writing to FIFO or verifying data from FIFO. There are five patterns to generate, i.e. all zero, all one, 32 bit increment data, 32 bit decrement data, and LFSR counter. All zero and all one are fixed value to select test data through Pattern Selector. While 32 bit increment data is designed by using 53 bit counter. The decrement data can be designed by connecting NOT logic to increment data. The LFSR pattern is designed by using LFSR counter. The equation of LFSR is  $x^{31} + x^{21} + x + 1$ . Data bus size of TestGen is 128 bit, so four 32-bit LFSR data must be generated within one clock. The logic to design LFSR must use look-ahead style to generate four LFSR data in the same clock.

To create unique test data for every 512 byte data, test pattern is designed as shown in Figure 2-4.

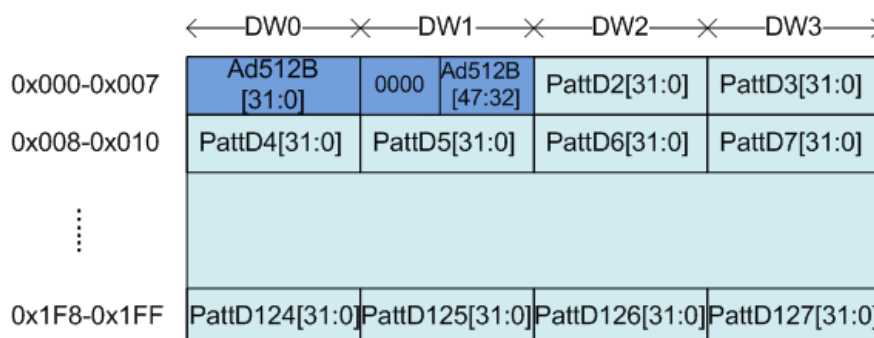


Figure 2-4 Test pattern format in each 512 byte data

512 byte data consists of two parts, i.e. 64 bit header in Dword#0 and Dword#1 and test data in Dword#2 – Dword#127. 64 bit header is created by using the address in 512 byte unit. So, Address counter inside TestData Generator is designed to generate the current address for 64 bit header data. The address counter loads the initial value, set by user. After that, the address counter is increment when finishing to transfer 512 byte data.

Test data is fed to be write data to the FIFO or the expected data comparing with the read data from FIFO. Fail flag is asserted to '1' when data verification is failed. The example of timing diagram to write data to FIFO is shown as follows.

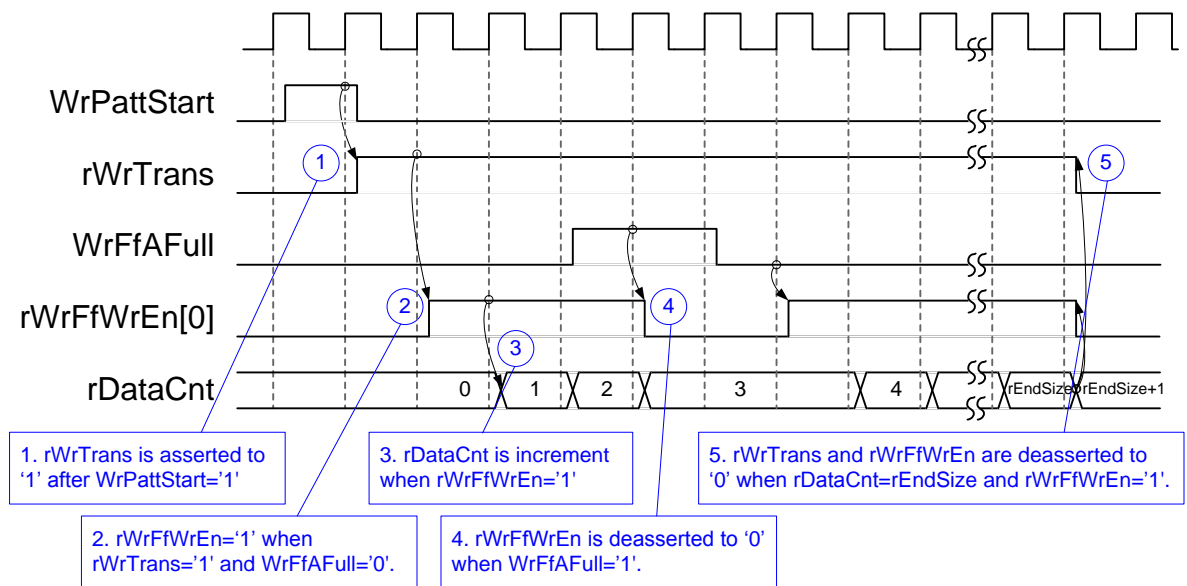


Figure 2-5 Timing diagram of Write operation in TestGen

- 1) WrPattStart is asserted to '1' for one clock cycle when user sets the register to start write operation. In the next clock, rWrTrans is asserted to '1' to enable the control logic for generating write enable to FIFO.
- 2) Write enable to FIFO (rWrFfWrEn) is asserted to '1' when two conditions are met. Firstly, rWrTrans must be asserted to '1' during the write operation being active. Secondly, the FIFO must not be full by monitoring WrFfAFull='0'.
- 3) The write enable is fed back to be counter enable to count total data in the write operation.
- 4) If FIFO is almost full (WrFfAFull='1'), the write process will be paused by de-asserting rWrFfWrEn to '0'.
- 5) When total data count is equal to the set value, rWrTrans is de-asserted to '0'. At the same time, rWrFfWrEn is also de-asserted to '0' to stop data generating.

For read timing diagram, read enable of FIFO is controlled by empty flag of FIFO. Comparing to write enable, the read enable signal is not stopped by total count and not started by start flag. When the read enable is asserted to '1', the data counter and address counter are also increment for counting total data and generating the header of expect value.

## 2.2 NVMe

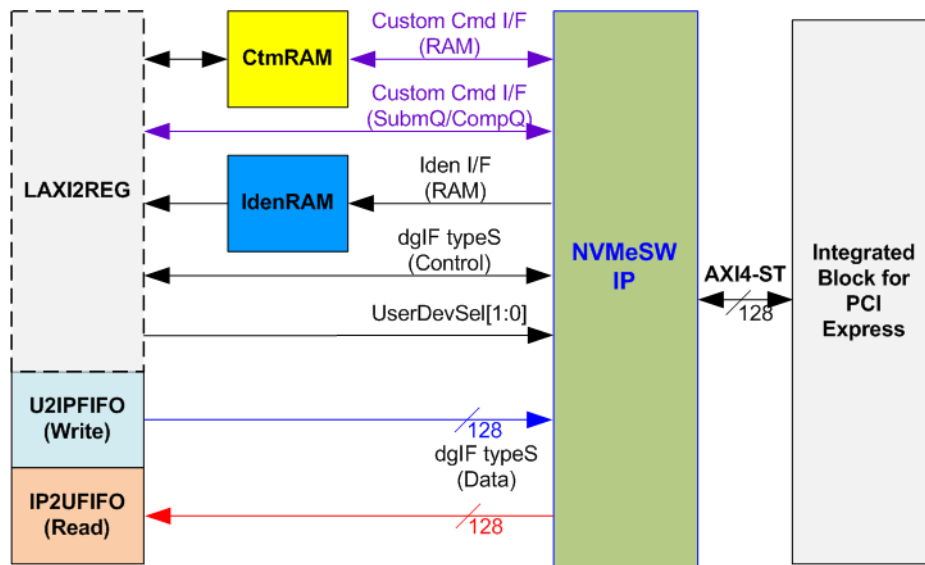


Figure 2-6 NVMe hardware

Figure 2-6 shows the example to interface NVMeSW IP in the reference design. The user interface of NVMeSW IP is split into control interface and data interface. The control interface receives the parameters of the command through custom command interface or dgIF typeS, depending on the command. Custom command interface is used when operating SMART command or Flush command.

The data interface of NVMeSW IP has four signal groups, i.e. custom command RAM interface, Identify interface, FIFO input interface (dgIF types), and FIFO output interface (dgIF types). Data bus width of all signal groups is 128 bit. The custom command RAM interface is bi-directional interface while the other interfaces are one directional interface. In the reference design, the custom command RAM interface is used to transfer data of SMART command from NVMeSW IP to LAXi2Reg only.

### 2.2.1 NVMeSW IP

The NVMeSW IP implements NVMe protocol of the host side to access one NVMe SSD directly or multiple SSDs through PCIe switch. The NVMeSW IP supports six commands, i.e. Write, Read, Identify, Shutdown, SMART, and Flush. NVMeSW IP can connect to the PCIe hard IP directly. More details of NVMeSW IP are described in datasheet.

[https://dgway.com/products/IP/NVMe-IP/dg\\_nvmeswip\\_data\\_sheet\\_en.pdf](https://dgway.com/products/IP/NVMe-IP/dg_nvmeswip_data_sheet_en.pdf)

### 2.2.2 Integrated Block for PCIe

This block is the hard IP in Xilinx device which implements Physical, Data Link, and Transaction Layers of PCIe specification. More details are described in Xilinx document.

PG156: UltraScale Devices Gen3 Integrated Block for PCI Express

PG213: UltraScale+ Devices Integrated Block for PCI Express



### 2.2.3 Dual port RAM

Two dual port RAM are implemented in the reference design to store data from Identify command and SMART command. The data size of Identify command is 8Kbyte, so IdenRAM size is 8Kbyte. NVMeSW IP and LAXi2Reg have different data bus size, so IdenRAM sets the different bus size for two interfaces. The data interface of NVMeSW IP is 128 bit while the interface of LAXi2Reg is 32 bit.

Otherwise, NVMeSW IP has double word enable to write only 32 bit data in some cases. The RAM setting on Xilinx IP tool supports the write byte enable. The small logic to convert double word enable to be write byte enable is designed as shown in Figure 2-7.

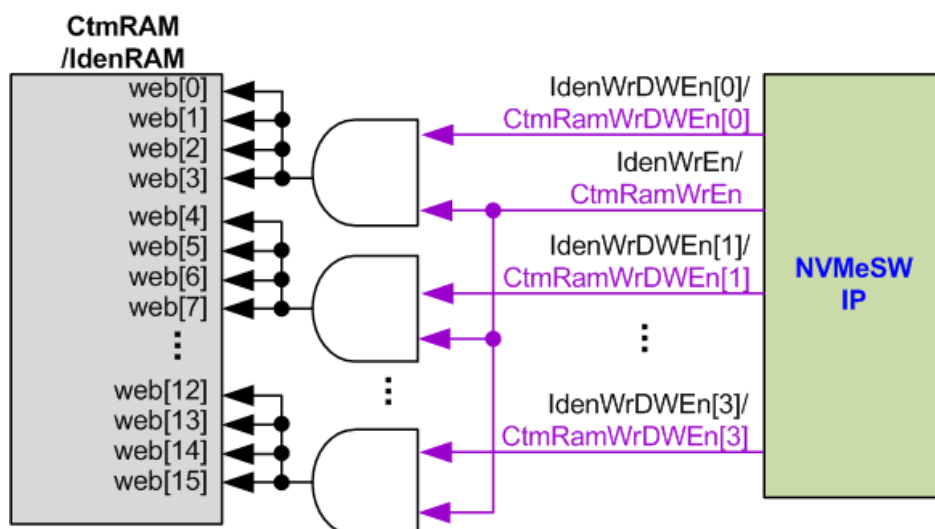


Figure 2-7 Byte write enable conversion logic

Bit[0] of WrDWEEn with WrEn signal are the inputs to AND logic. The output of AND logic is fed to bit[3:0] of IdenRAM byte write enable. Bit[1] of WrDWEEn is applied to generate bit[7:4] of IdenRAM write byte enable, and so on.

Similar to IdenRAM, CtmRAM is implemented by true dual-port RAM with byte write enable. The small logic to convert double word enable of custom interface to be byte write enable is applied as shown in Figure 2-7. But CtmRAM uses true dual-port RAM, not simple dual port RAM. This implementation is designed to support the additional custom command by using custom interface (supported as optional). For SMART command, the simple dual port RAM like IdenRAM could be used because data is transferred from NVMeSW IP to LAXi2Reg only. The data size of SMART command is 512 byte.

### 2.3 CPU and Peripherals

32 bit AXI4-Lite bus is applied to be the bus interface for CPU accessing the peripherals such as Timer and UART. To control and monitor the test logic of NVMeSW IP, the test logic is connected to CPU as a peripheral on 32 bit AXI4-Lite bus. CPU assigns the different base address and the address range for each peripheral.

In the reference design, the CPU system is built with one additional peripheral to access the test logic. The base address and the range for accessing the test logic are defined in the CPU system. So, the hardware logic must be designed to support AXI4-lite bus standard for writing and reading the register. LAXi2Reg module is designed to connect the CPU system as shown in Figure 2-8.

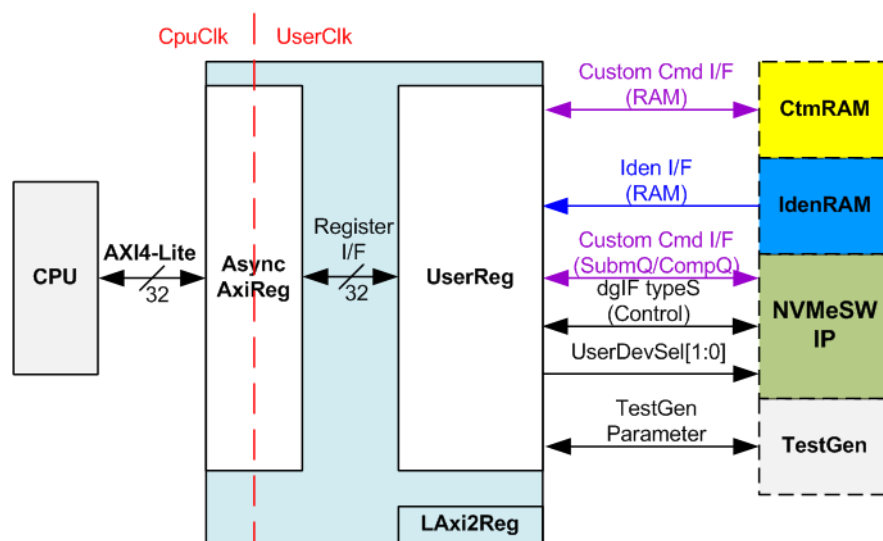


Figure 2-8 CPU and peripherals hardware

LAXi2Reg consists of AsyncAxiReg and UserReg. AsyncAxiReg is designed to convert the AXI4-Lite signals to be the simple register interface which has 32 bit data bus size (same as AXI4-Lite data bus size). Otherwise, AsyncAxiReg includes asynchronous logic to support clock crossing between CpuClk domain and UserClk domain.

UserReg includes the register file of the parameters and the status signals to control the other modules, i.e. CtmRAM, IdenRAM, NVMeSW IP, and TestGen. More details of AsyncAxiReg and UserReg are described as follows.

### 2.3.1 AsyncAxiReg

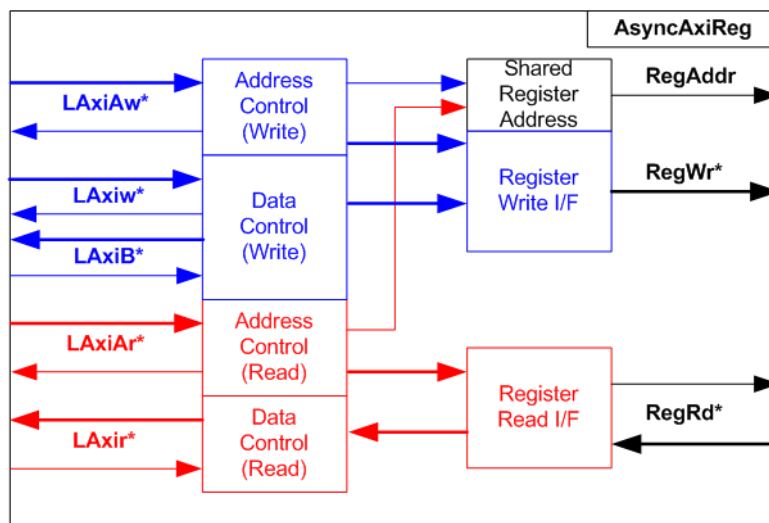


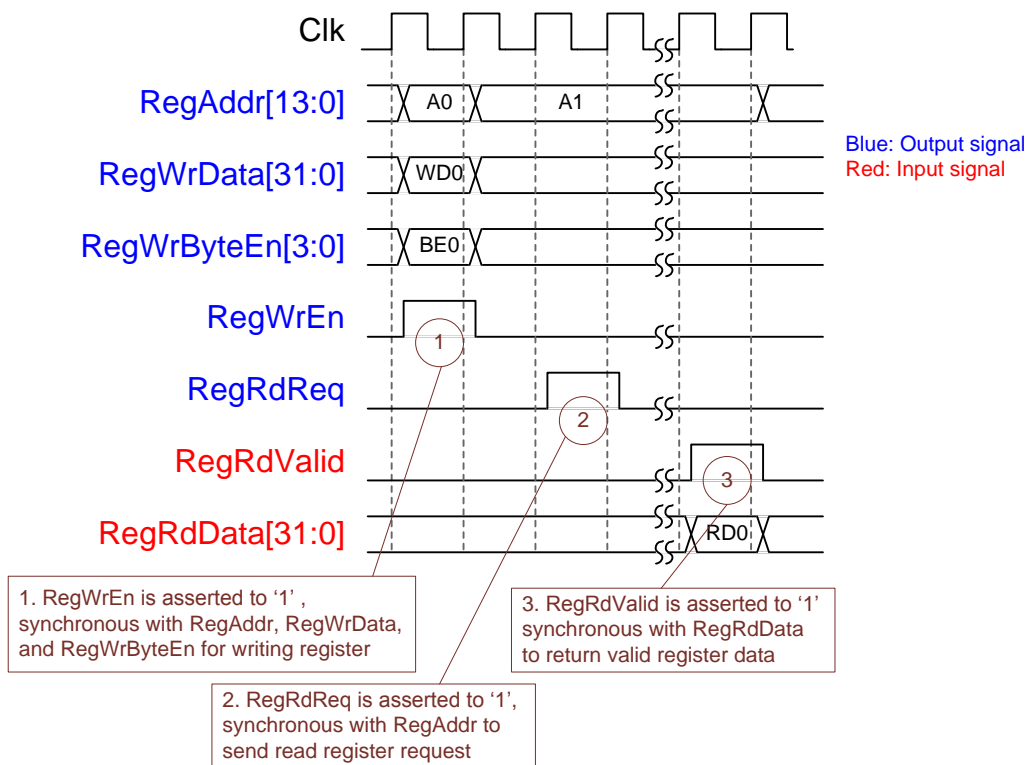
Figure 2-9 AsyncAxiReg Interface

The signal on AXI4-Lite bus interface can be split into five groups, i.e. LAXiAw\* (Write address channel), LAXiw\* (Write data channel), LAXiB\* (Write response channel), LAXiAr\* (Read address channel), and LAXir\* (Read data channel). More details to build custom logic for AXI4-Lite bus is described in following document.

[https://forums.xilinx.com/xlnx/attachments/xlnx/NewUser/34911/1/designing\\_a\\_custom\\_axi\\_slave\\_rev1.pdf](https://forums.xilinx.com/xlnx/attachments/xlnx/NewUser/34911/1/designing_a_custom_axi_slave_rev1.pdf)

According to AXI4-lite standard, the write channel and the read channel are operated independently. Also, the control and data interface of each channel are run parallel. So, the logic inside AsyncAxiReg to interface with AXI4-lite bus is split into four groups, i.e. Write control logic, Write data logic, Read control logic, and Read data logic as shown in the left side of Figure 2-9. Write control I/F and Write data I/F of AXI4-Lite bus are latched and transferred to be Write register interface with the shared register address. Otherwise, Read control I/F and Read data I/F of AXI4-Lite bus are latched and transferred to be Read register interface with the shared register address.

The simple register interface is designed to compatible to general RAM interface for write transaction. The read transaction of the register interface is little modified from RAM interface by adding RdReq signal. The address of register interface is shared for write and read transaction. So, user cannot write and read the register at the same time. The timing diagram of the register interface is shown in Figure 2-10.



**Figure 2-10 Register interface timing diagram**

- 1) To write register, the timing diagram is same as general RAM interface. RegWrEn is asserted to '1' with the valid signal of RegAddr (Register address in 32-bit unit), RegWrData (write data of the register), and RegWrByteEn (the write byte enable). Byte enable has four bit to be the byte data valid, i.e. bit[0] for RegWrData[7:0], bit[1] for RegWrData[15:8], and so on.
- 2) To read register, AsyncAxiReg asserts RegRdReq to '1' with the valid value of RegAddr. 32 bit data must be returned after receiving the read request. The slave must monitor RegRdReq signal to start the read transaction.
- 3) The read data is returned on RegRdData bus by the slave with asserting RegRdValid to '1'. After that, AsyncAxiReg forwards the read value to LAXir\* interface.

### 2.3.2 UserReg

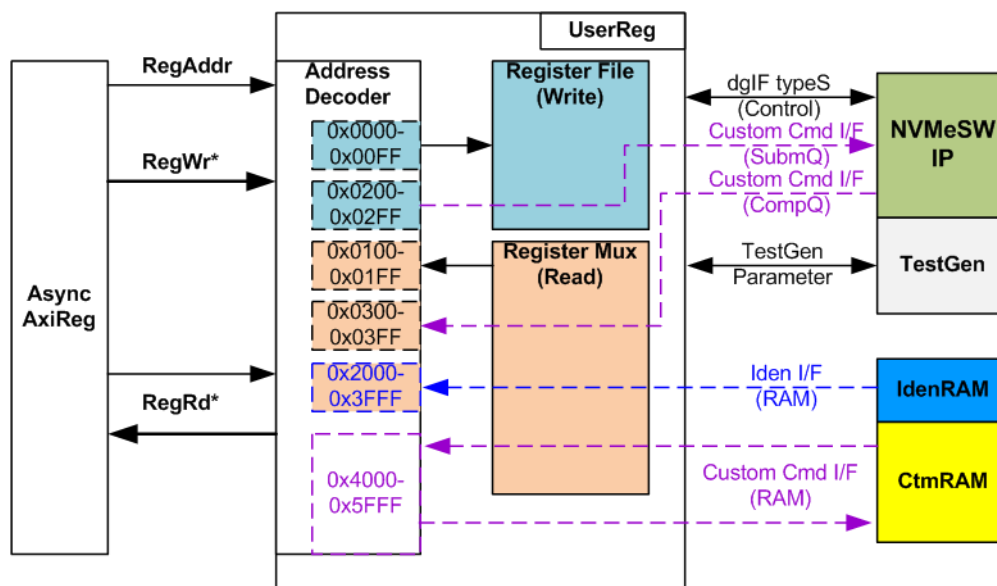


Figure 2-11 UserReg Interface

The address range to map to UserReg is split into six areas, as shown in Figure 2-11.

- 1) 0x0000 – 0x00FF: mapped to set the test parameters of NVMeSW IP and TestGen. This area is write access only.
- 2) 0x0200 – 0x02FF: mapped to set the test parameters of custom command interface (NVMeSW IP). This area is write access only.
- 3) 0x0100 – 0x01FF: mapped to read the status of NVMeSW IP and TestGen. This area is read access only.
- 4) 0x0300 – 0x03FF: mapped to read the status of custom command interface (NVMeSW IP). This area is read access only.
- 5) 0x2000 – 0x3FFF: mapped to read data from IdemRAM. This area is read access only.
- 6) 0x4000 – 0x5FFF: mapped to custom command RAM interface (NVMeSW IP). This area supports write access and read access. The demo shows only read access by running SMART command.

Address decoder decodes the upper bit of RegAddr for selecting the active hardware. The register file inside UserReg is 32 bit size, so write byte enable (RegWrByteEn) is not used. To set the parameters in the hardware, the CPU must use 32 bit pointer to force 32 bit valid value of the write data.

To read register, two step multiplexers are designed. Register Mux is the data multiplexer to select the read data within each address area. The lower bit of RegAddr is applied in the Register Mux. Next, the address decoder uses the upper bit to select the read data from each area for returning to CPU. Totally, the latency of read data is equal to two clock cycles, so RegRdValid is created by RegRdValid with asserting two D Flip-flops.

More details of the address mapping within UserReg module is shown in Table 2-1.

**Table 2-1 Register Map**

Address Wr/Rd	Register Name (Label in the "nvmeswiptest.c")	Description
<b>0x0000 – 0x00FF: Control signals of NVMeSW IP and TestGen (Write access only)</b>		
BA+0x0000	User Address (Low) Reg (USRADRL_REG)	[31:0]: Input to be start address as 512 byte unit (UserAddr[31:0] of dgIF typeS)
BA+0x0004	User Address (High) Reg (USRADRH_REG)	[15:0]: Input to be start address as 512 byte unit (UserAddr[47:32] of dgIF typeS)
BA+0x0008	User Length (Low) Reg (USRLENL_REG)	[31:0]: Input to be transfer length as 512 byte unit (UserLen[31:0] of dgIF typeS)
BA+0x000C	User Length (High) Reg (USRLENH_REG)	[15:0]: Input to be transfer length as 512 byte unit (UserLen[47:32] of dgIF typeS)
BA+0x0010	User Command Reg (USRCMD_REG)	[2:0]: Input to be user command (UserCmd of dgIF typeS for NVMeSW IP) "000": Identify, "001": Shutdown, "010": Write SSD, "011": Read SSD, "100": SMART, "110": Flush, "101"/"111": Reserved [9:8]: Input to select SSD number (UserDevSel[1:0] of NVMeSW IP) When this register is written, the command request is sent to NVMeSW IP to start the operation.
BA+0x0014	Test Pattern Reg (PATTSSEL_REG)	[2:0]: Test pattern select "000"-Increment, "001"-Decrement, "010"-All 0, "011"-All 1, "100"-LFSR
BA+0x0020	NVMe Timeout Reg (NVMTIMEOUT_REG)	[31:0]: Timeout value of NVMeSW IP (TimeOutSet[31:0] of NVMeSW IP)
<b>0x0100 – 0x01FF: Status signals of NVMeSW IP and TestGen (Read access only)</b>		
BA+0x0100	User Status Reg (USRSTS_REG)	[0]: UserBusy of dgIF typeS ('0': Idle, '1': Busy) [1]: UserError of dgIF typeS ('0': Normal, '1': Error) [2]: Data verification fail ('0': Normal, '1': Error) [19:16]: DevDetect[3:0] output from NVMeSW IP [25:24]: UserErrorDev[1:0] output from NVMeSW IP
BA+0x010C	User Error Type Reg (USRERRTYPE_REG)	[31:0]: User error status (UserErrorType[31:0] of dgIF typeS)
BA+0x0110	PCIe Status Reg (PCISTS_REG)	[0]: PCIe linkup status from PCIe hard IP ('0': No linkup, '1': linkup) [3:2]: PCIe link speed from PCIe hard IP ("00": Not linkup, "01": PCIe Gen1, "10": PCIe Gen2, "11": PCIe Gen3) [7:4]: PCIe link width status from PCIe hard IP ("0001": 1 lane, "0010": 2 lane, "0100": 4 lane, "1000": 8 lane) [13:8]: Current LTSSM State of PCIe hard IP. Please see more details of LTSSM value in Integrated Block for PCIe datasheet
BA+0x0114	Completion Status Reg (COMPSTS_REG)	[15:0]: Status from Admin completion (AdmCompStatus[15:0] of NVMeSW IP) [31:16]: Status from I/O completion (IOCompStatus[15:0] of NVMeSW IP)
BA+0x0118	NVMe CAP Reg (NVMCAP_REG)	[31:0]: NVMeCAPReg[31:0] output from NVMeSW IP
BA+0x0120	NVMeSW IP Test pin (Low) Reg (NVMTESTPIN_REG)	[31:0]: TestPin[31:0] output from NVMeSW IP
BA+0x0124	NVMeSW IP Test pin (High) Reg (NVMTESTPIN_REG)	[31:0]: TestPin[63:32] output from NVMeSW IP
BA+0x0130	Expected value Word0 Reg (EXPPATW0_REG)	[31:0]: Bit[31:0] of the expected data at the 1 <sup>st</sup> failure data in Read command
BA+0x0134	Expected value Word1 Reg (EXPPATW1_REG)	[31:0]: Bit[63:32] of the expected data at the 1 <sup>st</sup> failure data in Read command
BA+0x0138	Expected value Word2 Reg (EXPPATW2_REG)	[31:0]: Bit[95:64] of the expected data at the 1 <sup>st</sup> failure data in Read command
BA+0x013C	Expected value Word3 Reg (EXPPATW3_REG)	[31:0]: Bit[127:96] of the expected data at the 1 <sup>st</sup> failure data in Read command

Address Wr/Rd	Register Name (Label in the "nvmeswiptest.c")	Description
<b>0x0100 – 0x01FF: Status signals of NVMeSW IP and TestGen (Read access only)</b>		
BA+0x0140 Rd	Read value Word0 Reg (RDPATW0_REG)	[31:0]: Bit[31:0] of the read data at the 1 <sup>st</sup> failure data in Read command
BA+0x0144 Rd	Read value Word1 Reg (RDPATW1_REG)	[31:0]: Bit[63:32] of the read data at the 1 <sup>st</sup> failure data in Read command
BA+0x0148 Rd	Read value Word2 Reg (RDPATW2_REG)	[31:0]: Bit[95:64] of the read data at the 1 <sup>st</sup> failure data in Read command
BA+0x014C Rd	Read value Word3 Reg (RDPATW3_REG)	[31:0]: Bit[127:96] of the read data at the 1 <sup>st</sup> failure data in Read command
BA+0x0150 Rd	Data Failure Address(Low) Reg (RDFAILNOL_REG)	[31:0]: Bit[31:0] of the byte address of the 1 <sup>st</sup> failure data in Read command
BA+0x0154 Rd	Data Failure Address(High) Reg (RDFAILNOH_REG)	[24:0]: Bit[56:32] of the byte address of the 1 <sup>st</sup> failure data in Read command
BA+0x0158 Rd	Current test byte (Low) Reg (CURTESTSIZEL_REG)	[31:0]: Bit[31:0] of the current test data size in TestGen module
BA+0x015C Rd	Current test byte (High) Reg (CURTESTSIZEH_REG)	[24:0]: Bit[56:32] of the current test data size of TestGen module
BA+0x0180 Rd	Total device0 size (Low) Reg (LBASIZE0L_REG)	[31:0]: LBASize0[31:0] output from NVMeSW IP
BA+0x0184 Rd	Total device0 size (High) Reg (LBASIZE0H_REG)	[15:0]: LBASize0[47:32] output from NVMeSW IP [31]: LBAMode[0] output from NVMeSW IP
BA+0x0188 Rd	Total device1 size (Low) Reg (LBASIZE1L_REG)	[31:0]: LBASize1[31:0] output from NVMeSW IP
BA+0x018C Rd	Total device1 size (High) Reg (LBASIZE1H_REG)	[15:0]: LBASize1[47:32] output from NVMeSW IP [31]: LBAMode[1] output from NVMeSW IP
BA+0x0190 Rd	Total device2 size (Low) Reg (LBASIZE2L_REG)	[31:0]: LBASize2[31:0] output from NVMeSW IP
BA+0x0194 Rd	Total device2 size (High) Reg (LBASIZE2H_REG)	[15:0]: LBASize2[47:32] output from NVMeSW IP [31]: LBAMode[2] output from NVMeSW IP
BA+0x0198 Rd	Total device3 size (Low) Reg (LBASIZE3L_REG)	[31:0]: LBASize3[31:0] output from NVMeSW IP
BA+0x019C Rd	Total device3 size (High) Reg (LBASIZE3H_REG)	[15:0]: LBASize3[47:32] output from NVMeSW IP [31]: LBAMode[3] output from NVMeSW IP
<b>Other interfaces (Custom command of NVMeSW IP, IdenRAM, and Custom RAM)</b>		
BA+0x0200 - 0x023F Wr	Custom Submission Queue Reg (CTMSUBMQ_REG)	[31:0]: Submission queue entry of SMART and Flush command. Input to be CtmSubmDW0-DW15 of NVMeSW IP. 0x200: DW0, 0x204: DW1, ..., 0x23C: DW15
BA+0x0300 - 0x030F Rd	Custom Completion Queue Reg (CTMCOMPQ_REG)	[31:0]: CtmCompDW0-DW3 output from NVMeSW IP. 0x300: DW0, 0x304: DW1, ..., 0x30C: DW3
BA+0x0800 Rd	IP Version Reg (IPVERSION_REG)	[31:0]: IP version number (IPVersion[31:0] of NVMeSW IP)
BA+0x2000 - 0x2FFF Rd	Identify Controller Data (IDENCTRL_REG)	4Kbyte Identify controller data structure
BA+0x3000 - 0x3FFF Rd	Identify Namespace Data (IDENNAME_REG)	4Kbyte Identify Namespace Data Structure
BA+0x4000 - 0x5FFF Wr/Rd	Custom command Ram (CTMRAM_REG)	Connect to 8K byte CtmRAM interface. Used to store 512 byte data output from SMART command.



### 3 CPU Firmware

After system boot-up, CPU starts the initialization sequence as follows.

- 1) CPU initializes UART and Timer parameters.
- 2) CPU waits until PCIe connection links up (PCISTS\_REG[0]='1').
- 3) CPU waits until NVMeSW IP completes initialization process (USRSTS\_REG[0]='0'). If some errors are found, the process will stop with displaying the error message.
- 4) CPU displays PCIe link status (the number of PCIe lanes and the PCIe speed) by reading PCISTS\_REG[7:2]. Also, CPU displays total number of detected SSDs by reading USRSTS\_REG[19:16].
- 5) CPU displays the main menu. There are six menus for running six commands of NVMeSW IP, i.e. Identify, Write, Read, SMART, Flush, and Shutdown.

More details of the sequence in each command are described as follows.

#### 3.1 Identify Command

The sequence of the firmware when user selects Identify command is below.

- 1) Receive device number through Serial console. If the input is invalid, the operation will be cancelled.  
*Note: User can select to run all devices. In this mode, the firmware runs step 2) - 4) of Identify command many times until total devices are operated completely.*
- 2) Set USRCMD\_REG[2:0]="000" and USRCMD\_REG[9:8]=device number. When USRCMD\_REG is set, NVMeSW IP will receive the new command request. So, busy flag (USRSTS\_REG[0]) changes from '0' to '1'.
- 3) CPU waits until the operation is completed or some errors are found by monitoring USRSTS\_REG[1:0].

Bit[0] is de-asserted to '0' when command is completed. If the command is completed, the data from Identify command of NVMeSW IP will be stored in IdenRAM.

Bit[1] is asserted to '1' when some errors are detected. The error message is displayed on the console to show the error device number (read from USRSTS\_REG[25:24]) and the error details (read from USRERRTYPE\_REG[31:0]). Finally, the process is stopped.

- 4) After busy flag (USRSTS\_REG[0]) is de-asserted to '0', CPU displays some information from IdenRAM (IDENCTRL\_REG) such as SSD model name and the information from NVMeSW IP output, i.e. SSD capacity and LBA unit size (LBASIZE\_REG) of the active device.



### 3.2 Write/Read Command

The sequence of the firmware when user selects Write/Read command is below.

- 1) Receive start address, transfer length, test pattern, and device number through Serial console. If some inputs are invalid, the operation will be cancelled.

*Note: If LBA unit size = 4 Kbyte, start address and transfer length must be aligned to 8.*

- 2) Get all inputs and set the value to USRADRL/H\_REG, USRLENL/H\_REG, and PATTSEL\_REG.
- 3) Set USRCMD\_REG[2:0]="010" for Write command or "011" for Read command, and USRCMD\_REG[9:8]=device number. When USRCMD\_REG is set, NVMeSW IP will receive the new command request. So, busy flag (USRSTS\_REG[0]) changes from '0' to '1'.
- 4) CPU waits until the operation is completed or some errors (except verification error) are found by monitoring USRSTS\_REG[2:0].

Bit[0] is de-asserted to '0' when command is completed.

Bit[1] is asserted when error is detected. After that, error message is displayed on the console to show the error details. Finally, the process will be hanged up.

Bit[2] is asserted when data verification is fail. Then, the verification error message is displayed. CPU is still running until the operation is done or user inputs any key to cancel operation.

During running command, current transfer size reading from CURTESTSIZE\_REG is displayed every second.

- 5) After busy flag (USRSTS\_REG[0]) is de-asserted to '0', CPU display the test result on the console, i.e. total time usage, total transfer size, and transfer speed.

### 3.3 SMART Command

The sequence of the firmware when user selects SMART command is below.

- 1) Receive device number through Serial console. If the input is invalid, the operation will be cancelled.  
*Note: User can select to run all devices. In this mode, the firmware runs step 2) - 5) of SMART command many times until total devices are operated completely.*
- 2) Set 16 Dwords of Submission queue entry (CTMSUBMQ\_REG) to be SMART command value.
- 3) Set USRCMD\_REG[2:0]="100" and USRCMD\_REG[9:8]=device number. When USRCMD\_REG is set, NVMeSW IP will receive the new command request. So, busy flag (USRSTS\_REG[0]) changes from '0' to '1'.
- 4) CPU waits until the operation is completed or some errors are found by monitoring USRSTS\_REG[1:0].

Bit[0] is de-asserted to '0' when command is completed. If the command is completed, the data from SMART command of NVMeSW IP will be stored in CtmRAM.

Bit[1] is asserted when error is detected. The error message is displayed on the console to show the error device number (read from USRSTS\_REG[25:24]) and the error details (read from USRERRTYPE\_REG[31:0]). Finally, the process is stopped.

- 5) After busy flag (USRSTS\_REG[0]) is de-asserted to '0', CPU displays some information from CtmRAM (CTMRAM\_REG), i.e. Temperature, Total Data Read, Total Data Written, Power On Cycles, Power On Hours, and Number of Unsafe Shutdown.

More details of SMART log are described in NVM Express Specification.

<https://nvmexpress.org/resources/specifications/>

### 3.4 Flush Command

The sequence of the firmware when user selects Flush command is below.

- 1) Receive device number through Serial console. If the input is invalid, the operation will be cancelled.  
*Note: User can select to run all devices. In this mode, the firmware runs step 2) - 4) of Flush command many times until total devices are operated completely.*
- 2) Set 16 Dwords of Submission queue entry (CTMSUBMQ\_REG) to be Flush command value.
- 3) Set USRCMD\_REG[2:0]="110" and USRCMD\_REG[9:8]=device number. When USRCMD\_REG is set, NVMeSW IP will receive the new command request. So, busy flag (USRSTS\_REG[0]) changes from '0' to '1'.
- 4) CPU waits until the operation is completed or some errors are found by monitoring USRSTS\_REG[1:0].

Bit[0] is de-asserted to '0' when command is completed. If the command is completed, CPU will go back to the main menu.

Bit[1] is asserted when error is detected. The error message is displayed on the console to show the error device number (read from USRSTS\_REG[25:24]) and the error details (read from USRERRTYPE\_REG[31:0]). Finally, the process is stopped.

### 3.5 Shutdown Command

The sequence of the firmware when user selects Shutdown command is below.

- 1) Receive device number through Serial console. If the input is invalid, the operation will be cancelled.  
*Note: User can select to run all devices. In this mode, the firmware runs step 2) - 4) of Shutdown command many times until total devices are operated completely.*
- 2) Set USRCMD\_REG[2:0]="001" and USRCMD\_REG [9:8] =device number. When USRCMD\_REG is set, NVMeSW IP will receive the new command request. So, busy flag (USRSTS\_REG[0]) changes from '0' to '1'.
- 3) CPU waits until the operation is completed or some errors are found by monitoring USRSTS\_REG[1:0].

Bit[0] is de-asserted to '0' when command is completed. After that, the CPU goes to the next step.

Bit[1] is asserted when error is detected. The error message is displayed on the console to show the error device number (read from USRSTS\_REG[25:24]) and the error details (read from USRERRTYPE\_REG[31:0]). Finally, the process is stopped.

- 4) After busy flag (USRSTS\_REG[0]) is de-asserted to '0', the selected SSD changes to inactive status. CPU updates total numbers of device in the system by reading USRSTS\_REG[19:16], and then displays the updated information on the console.

If there is no active SSD in the system, NVMeSW IP will go to inactive state. The CPU cannot receive new command from user. The user must power off the test system.

## 4 Example Test Result

The example test result when running the demo system by using 512 GB Samsung 970 Pro is shown in Figure 4-1.

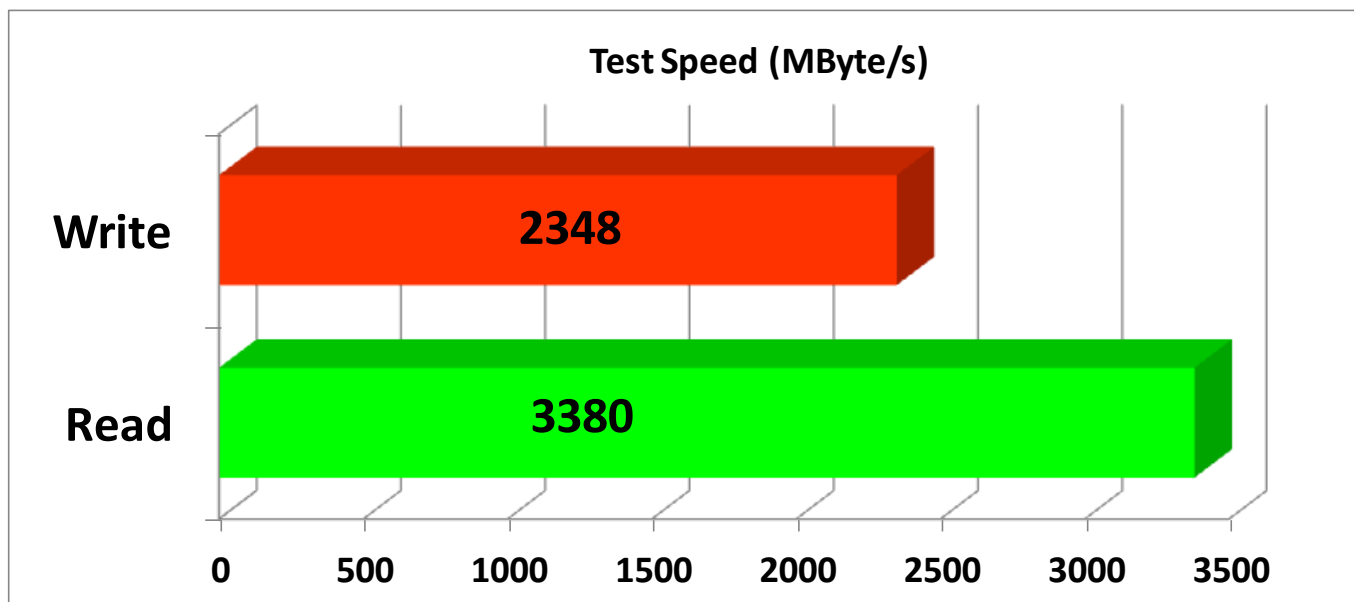


Figure 4-1 Test Performance of NVMeSW IP demo by using Samsung 970 Pro SSD

By using PCIe Gen3 on KCU105 board, write performance is 2345 Mbyte/sec and read performance is 3380 Mbyte/sec.



## 5 Revision History

Revision	Date	Description
1.0	24-Apr-2019	Initial Release

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